

RobustLine rotary actuator failsafe and extended functionalities for adjusting dampers in technical building installations and laboratories

- Air damper size up to approx. 1.2 m<sup>2</sup>
- Torque motor 6 Nm
- Nominal voltage AC/DC 24 V
- Control Open/close

**Technical data** 

- Running time motor 4 s
- Optimum protection against corrosion and chemical influences, UV radiation, damp and condensation



Nominal voltage  Nominal voltage frequency	AC/DC 24 V
Nominal voltage frequency	
	50/60 Hz
Nominal voltage range	AC 19.228.8 V / DC 21.628.8 V
Power consumption in operation	11 W
Power consumption in rest position	3 W
Power consumption for wire sizing	22 VA
	Cable 1 m, 3 x 0.75 mm <sup>2</sup> (halogen-free)
	Yes (note the performance data)
•	6 Nm
	0100%, adjustable in increments of 10%
county run care position	(POP rotary knob on 0 corresponds to left end
	stop)
Position accuracy	±5%
Direction of motion motor	selectable with switch 0 (ccw rotation) / 1 (cw
	rotation)
Direction of motion fail-safe	selectable with switch 0100%
Manual override	with push-button, can be locked
Angle of rotation	Max. 95°
Angle of rotation note	can be limited on both sides with adjustable
	mechanical end stops
Minimum angle of rotation	Min. 30°
Running time motor	4 s / 90°
Running time fail-safe	4 s / 90°
Running time fail-safe note	<4 s @ 050°C
Adaptation setting range	manual (automatic on first power-up)
Sound power level, motor	60 dB(A)
Sound power level, fail-safe	60 dB(A)
Mechanical interface	Universal shaft clamp 820 mm
Position indication	Mechanically, pluggable
Protection class IEC/EN	III Safety Extra-Low Voltage (SELV)
	UL Class 2 Supply
	IP66/67
	NEMA 4X
	UL Enclosure Type 4X
	CE according to 2014/30/EU
	IEC/EN 60730-1 and IEC/EN 60730-2-14
	Type 1.AA
	0.8 kV
	4
	-3050°C
	-4080°C
	Max. 100% r.H.
-	maintenance-free
Woight	2.2 kg
Weight Abbreviations	2.3 kg POP = Power off position / fail-safe position
	Connection supply / control Parallel operation  Torque motor Setting fail-safe position  Position accuracy Direction of motion motor  Direction of motion fail-safe Manual override Angle of rotation Angle of rotation note  Minimum angle of rotation Running time motor Running time fail-safe Running time fail-safe note Adaptation setting range Sound power level, motor Sound power level, fail-safe Mechanical interface

PF = Power fail delay time / bridging time



### Safety notes



- The device must not be used outside the specified field of application, especially not in aircraft or in any other airborne means of transport.
- Only authorised specialists may carry out installation. All applicable legal or institutional installation regulations must be complied during installation.
- Junction boxes must at least correspond with enclosure IP degree of protection!
- The cover of the protective housing may be opened for adjustment and servicing.
   When it is closed afterwards, the housing must seal tight (see installation instructions).
- The device may only be opened at the manufacturer's site. It does not contain any parts that can be replaced or repaired by the user.
- The cables must not be removed from the device installed in the interior.
- To calculate the torque required, the specifications supplied by the damper manufacturers concerning the cross-section, the design, the installation site and the ventilation conditions must be observed.
- The device contains electrical and electronic components and must not be disposed
  of as household refuse. All locally valid regulations and requirements must be
  observed.
- The information on chemical resistance refers to laboratory tests with raw materials and finished products and to trials in the field in the areas of application indicated.
- The materials used may be subjected to external influences (temperature, pressure, constructional fixture, effect of chemical substances, etc.), which cannot be simulated in laboratory tests or field trials.
- Self adaption is necessary when the system is commissioned and after each adjustment of the angle of rotation (press the adaption push-button once).
- The information regarding areas of application and resistance can therefore only serve as a guideline. In case of doubt, we definitely recommend that you carry out a test. This information does not imply any legal entitlement. Belimo will not be held liable and will provide no warranty. The chemical or mechanical resistance of the materials used is not alone sufficient for judging the suitability of a product. Regulations pertaining to combustible liquids such as solvents etc. must be taken into account with special reference to explosion protection.
- Flexible metallic cable conduits or threaded cable conduits of equal value are to be used for UL (NEMA) Type 4X applications.
- When used under high UV loads, e.g. extreme sunlight, the use of flexible metallic or equivalent cable conduits is recommended.

#### **Product features**

#### Fields of application

The actuator is particularly suitable for utilisation in outdoor applications and is protected against the following weather conditions:

- Wood drying
- Animal breeding
- Food processing
- Agriculture
- Indoor swimming pools / bathhouses
- Rooftop ventilation plant rooms
- General outdoor applications
- Alternating climate
- Laboratories

#### Resistances

Noxious gas test EN 60068-2-60 (Fraunhofer Institut ICT / DE) Salt fog spray test EN 60068-2-52 (Fraunhofer Institut ICT / DE)

Ammoniac test DIN 50916-2 (Fraunhofer Institut ICT / DE) Climate test IEC60068-2-30 (Trikon Solutions AG / CH)

Disinfectant (animals) (Trikon Solutions AG / CH)

UV Test (Solar radiation at ground level) EN 60068-2-5, EN 60068-2-63 (Quinel / Zug CH)



#### **Product features**

**Used materials** Actuator housing polypropylene (PP)

Cable glands / hollow shaft polyamide (PA)

Connecting cable FRNC

Clamp / screws in general Steel 1.4404

Seals EPDM

Form fit insert aluminium anodised

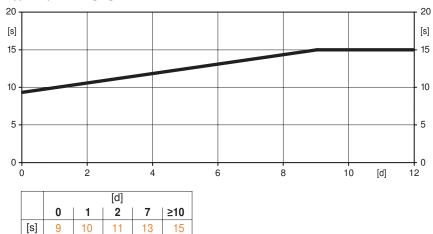
Mode of operation

The actuator moves the damper to the desired operating position at the same time as the integrated capacitors are charged. Interrupting the supply voltage causes the damper to be rotated back into the fail-safe position by means of stored electrical energy.

Pre-charging time (start up)

The capacitor actuators require a pre-charging time. This time is used for charging the capacitors up to a usable voltage level. This ensures that, in the event of a power failure, the actuator can move at any time from its current position into the preset failsafe position. The duration of the pre-charging time depends mainly on how long the power was interrupted.

Typical pre-charging times



[d] = Electricity interruption in days [s] = Pre-charging time in seconds PF[s] = Bridging time

**Delivery condition (capacitors)** 

The actuator is completely discharged after delivery from the factory, which is why the actuator requires approximately 15 s pre-charging time before initial commissioning in order to bring the capacitors up to the required voltage level.

Simple direct mounting

Simple direct mounting on the damper shaft with a universal shaft clamp, supplied with an anti-rotation device to prevent the actuator from rotating.

Manual override

Manual control with push-button possible - temporary. The gear is disengaged and the actuator decoupled for as long as the button is pressed.

Adjustable angle of rotation

Adjustable angle of rotation with mechanical end stops. A minimum permissible angle of rotation of 30° must be allowed for.

High functional reliability

The actuator is overload protected, requires no limit switches and automatically stops when the end stop is reached.

Home position

The first time the supply voltage is switched on, i.e. at the time of commissioning, the actuator carries out an adaption, which is when the operating range and position feedback adjust themselves to the mechanical setting range.

The detection of the mechanical end stops enables a gentle approach to the end positions, thus protecting the actuator mechanics.

The actuator then moves into the position defined by the positioning signal.

Setting direction of rotation

When actuated, the direction of the rotation switch changes the running direction in normal operation. The direction of the rotation switch has no influence on the fail-safe position which has been set.

Setting fail-safe position (POP)

The rotary knob fail-safe position can be used to adjust the desired fail-safe position 0...100% in 10% increments. The rotary knob always refers to the adapted angle of rotation range. In the event of a power failure, the actuator will move into the selected fail-safe position.

Adaption and synchronisation

An adaption can be triggered manually by pressing the "Adaption" button. Both mechanical end stops are detected during the adaption (entire setting range).

# Rotary actuator (RobustLine) fail-safe, Open/close, AC/ DC 24 V, 6 Nm, Running time motor 4 s



# **Electrical installation**

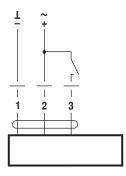


### **Notes**

- Connection via safety isolating transformer.
- Parallel connection of other actuators possible. Observe the performance data.

### Wiring diagrams

AC/DC 24 V, open/close

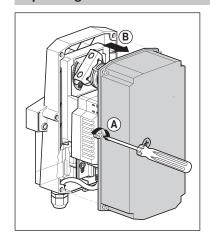


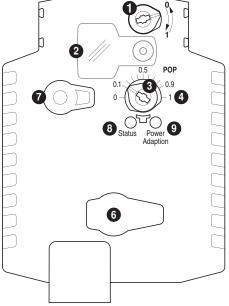
## Cable colours:

- 1 = black
- 2 = red
- 3 = white



# Operating controls and indicators



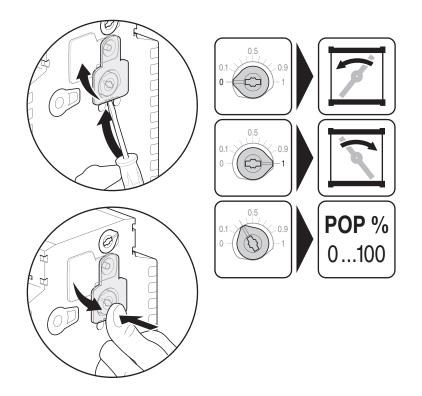


- 1 Direction of rotation switch
- 2 Cover, POP button
- 3 POP button
- 4 Scale for manual adjustment
- 6 (no function)
- 7 Disengagement button

LED displays  8 yellow 9 green		Meaning / function	
Off	On	Operation OK / without fault	
Off	Flashing	POP function active	
On	Off	Fault	
Off	Off	Not in operation	
On	On	Adaptation procedure running	

Press button: Triggers angle of rotation adaption, followed by standard operation

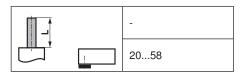
Setting emergency setting position (POP)





# Dimensions [mm]

# Spindle length



# Clamping range

<u>OI</u>	<b>_</b>	$\Diamond$
820	814	1020

# **Dimensional drawings**

